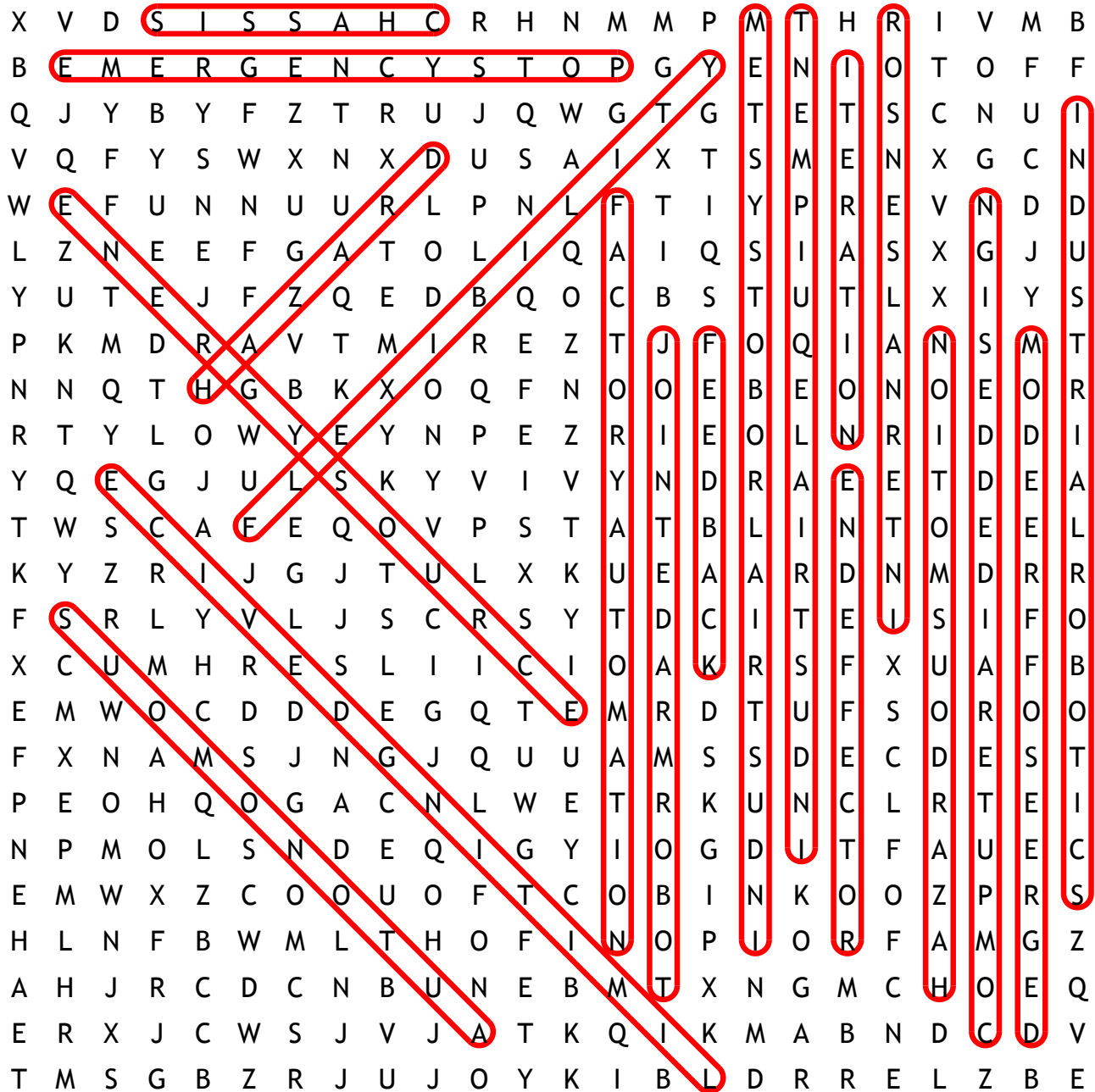


Name: _____

Date: _____

Basic Robotics



Industrial Robot System
Industrial Robotics
Jointed Arm Robot
Internal Sensor
End-Effector
Iteration
Hazard

Computer-Aided Design
Factory Automation
Hazardous Motion
Emergency Stop
Flexibility
Feedback

Industrial Equipment
Degrees of Freedom
Limiting Device
Energy Source
Autonomous
Chassis