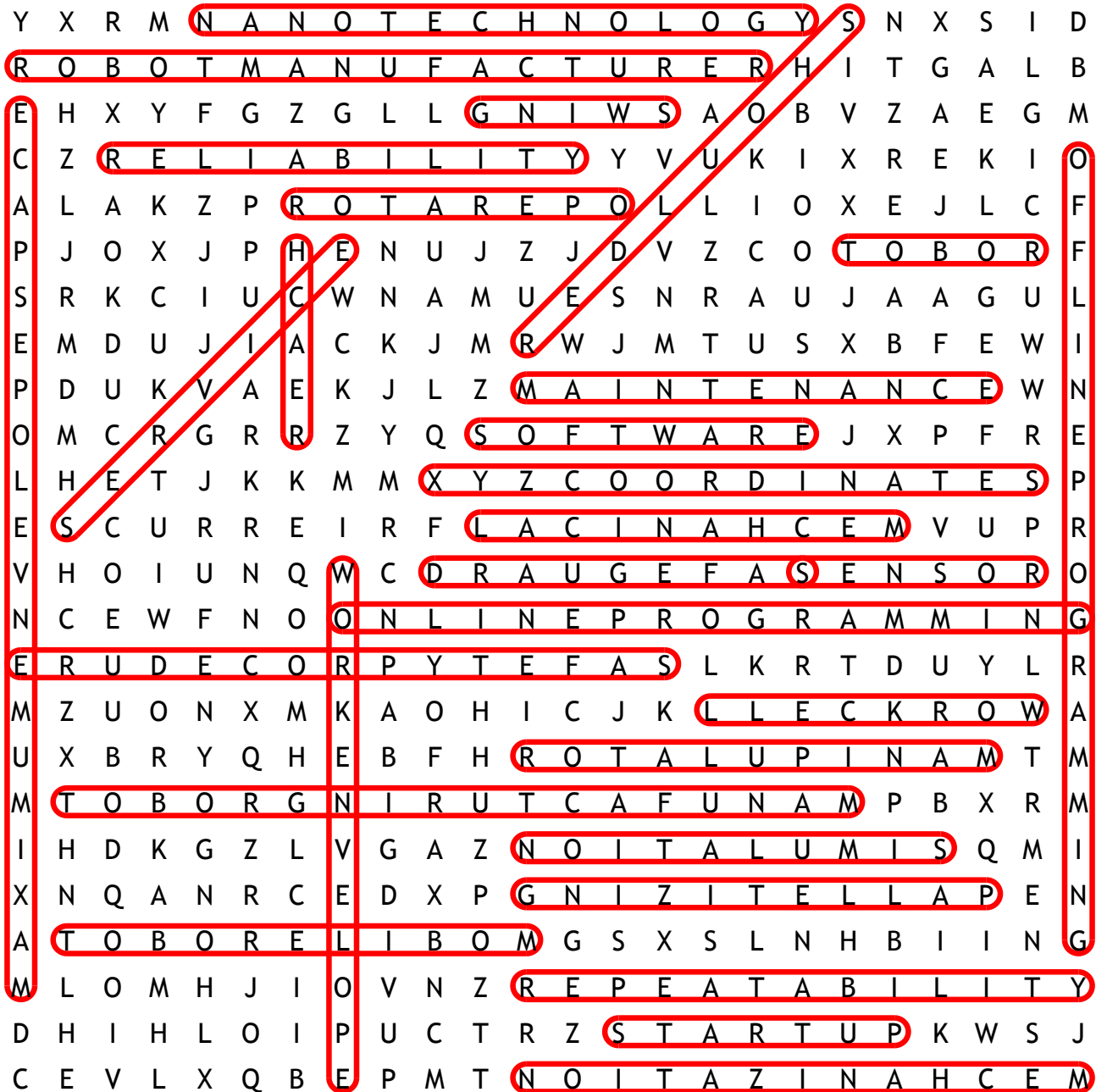


Name: _____

Date: _____

Basic Robotics PT. 2



Maximum Envelope Space
 Robot Manufacturer
 Work Envelope
 Reliability
 Simulation
 Start-up
 Service
 Reach

Off-Line Programming
 Safety Procedure
 Repeatability
 Palletizing
 Mechanical
 Software
 Sensor

On-Line Programming
 XYZ Coordinates
 Mechanization
 Manipulator
 Work Cell
 Shoulder
 Swing

Manufacturing Robot
 Nanotechnology
 Mobile Robot
 Maintenance
 Safeguard
 Operator
 Robot