

Name: _____

Date: _____

robotics

U	E	R	C	P	Q	S	X	Q	X	Z	X	F	O	B	Q	K	P	Y	F	J	G	I	D
Q	H	P	D	C	H	L	Y	B	D	B	D	N	D	L	T	I	R	S	S	B	S	D	R
C	P	C	B	Q	D	L	H	Y	D	R	A	U	L	I	C	X	L	D	F	N	O	H	X
R	P	L	L	J	B	P	X	W	R	X	P	A	H	E	Y	Q	R	P	Z	O	F	V	A
H	U	V	R	K	M	H	H	L	U	D	X	Y	L	F	Z	W	R	V	Z	I	K	M	Y
P	G	E	W	F	K	A	G	S	I	Z	G	A	Q	J	R	V	O	Y	Y	T	I	K	L
I	J	Z	H	X	U	D	N	I	I	H	D	E	Z	Y	R	W	C	R	A	A	V	T	A
W	F	R	B	K	Z	S	I	F	T	H	D	T	E	R	L	W	J	W	W	M	H	K	D
A	C	C	I	T	A	M	U	E	N	P	X	N	E	J	F	B	K	G	W	O	U	Y	V
Z	J	C	B	A	C	K	P	S	R	E	T	O	O	L	I	N	G	S	W	T	W	J	Z
P	G	W	O	R	K	E	N	V	E	L	O	P	E	H	C	T	I	P	P	U	C	O	I
V	R	O	L	L	H	R	Z	D	C	Z	A	D	V	N	F	Q	X	I	R	A	F	I	Q
R	Q	P	L	W	S	C	I	T	O	B	O	R	R	M	M	E	R	O	B	O	T	N	X
G	P	Y	P	K	O	T	N	D	N	Q	N	P	L	U	W	H	A	P	V	A	C	T	H
V	D	L	W	B	Z	Z	P	V	D	O	C	B	V	S	T	J	S	M	Z	M	P	E	G
V	G	W	R	H	G	A	X	E	S	B	O	N	V	W	U	B	Y	U	T	J	X	D	X
C	R	G	E	N	R	E	T	U	P	M	O	C	U	W	J	R	W	X	R	P	E	A	G
W	I	V	Y	W	J	T	Q	Q	E	L	F	I	L	J	F	W	V	C	P	W	C	R	N
I	P	U	K	L	Z	L	C	Y	Q	R	K	S	Z	M	Z	H	C	W	S	Y	C	M	J
Z	P	I	M	S	M	E	F	M	B	Q	M	P	O	G	O	Y	L	A	M	B	W	G	F
Q	E	S	B	J	A	N	D	R	O	I	D	U	P	T	N	B	D	Y	F	W	K	E	H
K	R	N	U	P	H	O	T	O	S	E	N	S	O	R	K	L	D	J	G	S	E	O	B
F	A	R	T	I	F	I	C	I	A	L	I	N	T	E	L	L	I	G	E	N	C	E	H
A	U	E	E	X	Z	U	E	J	G	N	I	L	O	O	T	M	R	A	F	O	D	N	E

artificial intelligence
photo sensor
retooling
computer
android
roll

end of arm tooling
jointed arm
hydraulic
robotics
pitch
axes

work envelope
automation
pneumatic
gripper
robot
yaw