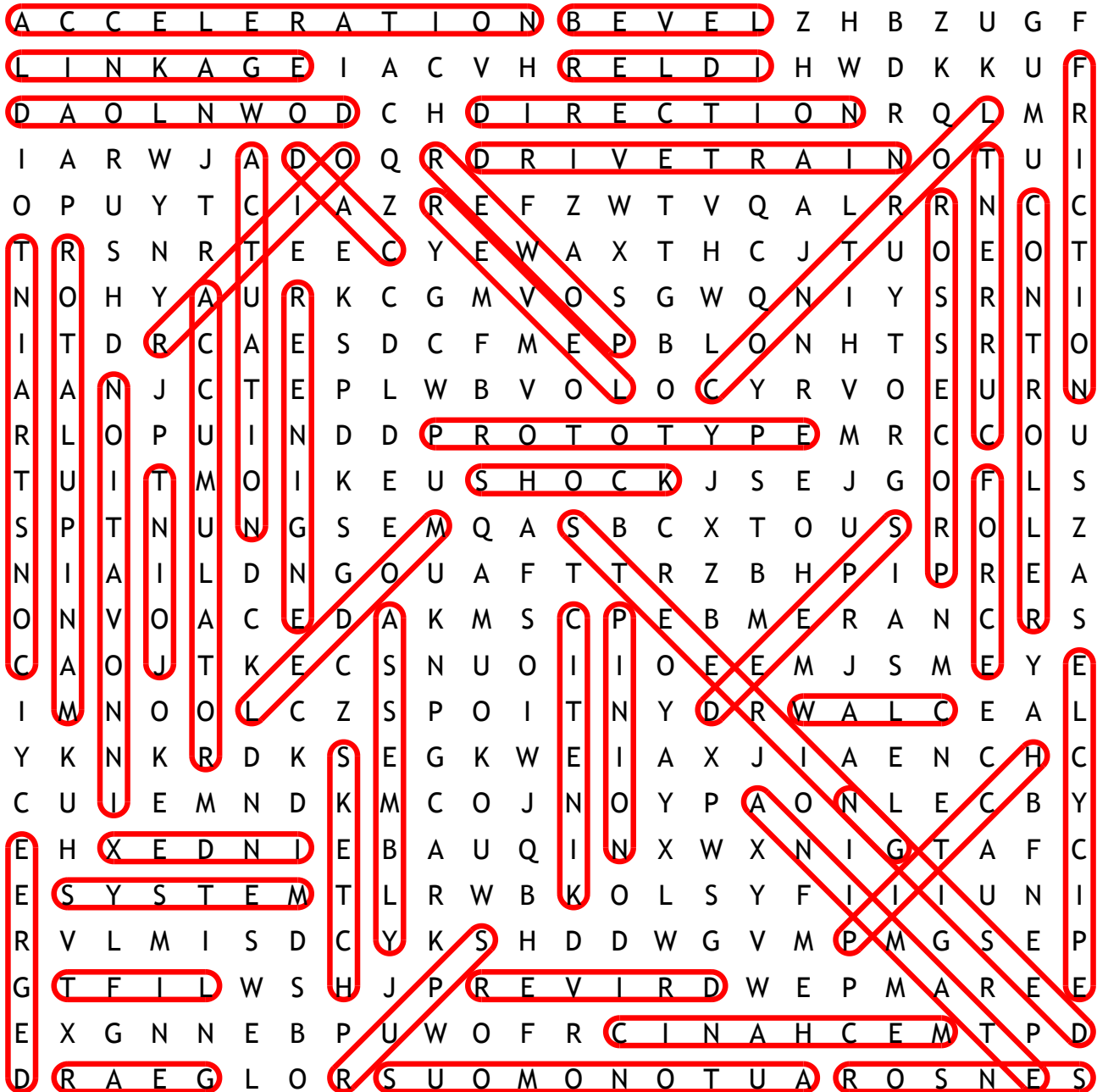


Name: _____

Date: _____

Vex robotics



ACCELERATION	MANIPULATOR	ACCUMULATOR	INNOVATION	DRIVETRAIN	CONTROLLER
CONSTRAINT	AUTONOMOUS	PROTOTYPE	PROCESSOR	DIRECTION	ACTUATION
STEERING	MECHANIC	FRICTION	EPICYCLE	ENGINEER	DOWNLOAD
ASSEMBLY	LINKAGE	KINETIC	CURRENT	CONTROL	ANIMATE
SYSTEM	SKETCH	SENSOR	PINION	DRIVER	DESIGN
DEGREE	SPEED	SHOCK	RATIO	POWER	PITCH
MODEL	LEVER	JOINT	INDEX	IDLER	FORCE
BEVEL	SPUR	LIFT	GEAR	CLAW	CAD