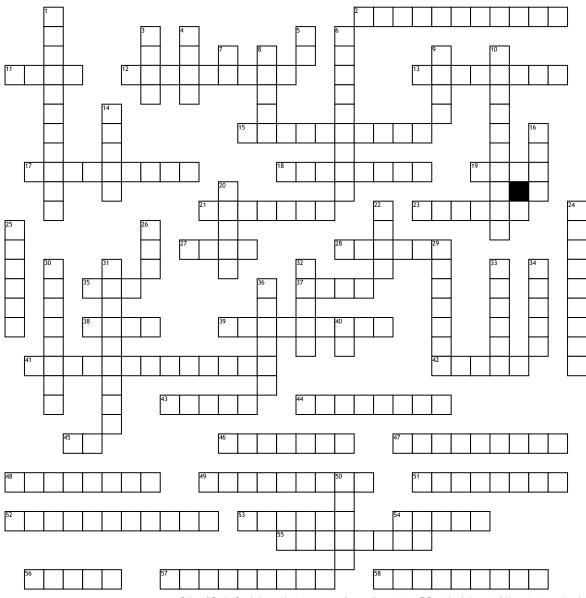
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## POE - 2.1: Key Term Word Crossword



## Across

Statically Indeterminate A structure or body which is over-constrained such that there are more unknown supports than there are equations of static

- 11. Moment of Inertia A mathematical property of a cross section that is concerned with a surface area and how that area is distributed about a centroidal
- 12. Pinned Support A support that prevents translation in any
- 13. Vector
- ${\bf 15}.$  Cable A strong rope, usually made of metal, designed to have great tensile strength and to be used in
- ${\bf 17.}\ {\bf Roller}\ {\bf Support}\ {\bf A}\ {\bf support}\ {\bf that}\ {\bf only}\ {\bf prevents}\ {\bf a}\ {\bf beam}\ {\bf from}\ {\bf translating}\ {\bf in}\ {\bf one}$
- $\textbf{18.} \ A \ condition \ where \ there \ are \ no \ net \ external \ forces \ acting \ upon \ a \ particle \ or \ rigid \ body \ and \ the \ body \ remains \ at \ rest \ or \ continues \ at \ a \ constant$
- 19. A body subjected to a
- ${\bf 21.}$  Planar Truss A truss that lies in a single plane often used to support roofs and
- ${\bf 23.}\ {\bf Magnitude}\ {\bf The}\ {\bf absolute}\ {\bf value}\ {\bf of}\ {\bf a}$
- 27. Compression Force A body subjected to a
- 28. Member Slender straight pieces of a truss connected by
- 35. Method of Joints A method of analysis of trusses which constructs free body diagrams of each joint and determines the forces acting in that joint by considering equilibrium of the joint
- ${\bf 37.}\ {\bf A}\ {\bf physical}\ {\bf quantity}\ {\bf that}\ {\bf has}\ {\bf magnitude}$
- 38. Fixed Support A support that prevents translation and rotation in a
- ${\bf 39.}~{\rm A}~{\rm quantity}~{\rm that}~{\rm has}~{\rm both}~{\rm a}~{\rm magnitude}~{\rm and}$
- 41. Statically
- 42. Joint The connection points of members of a
- ${\bf 43.} \ Newton's \ Second \ Law \ The \ change \ of \ motion \ of \ the \ body \ is \ proportional \ to \ the \ net \ force imposed \ on \ the \ body \ and \ is \ in \ the \ direction \ of \ the \ net$
- ${\bf 44.} \ Structure \ Something \ made \ up \ of \ interdependent \ parts \ in \ a \ definite \ pattern \ of \ organization, \ such \ as \ trusses, \ frames, \ or$

- 45. Newton's First Law Every body or particle continues at a state of rest or uniform motion in a straight line, unless it is compelled to change that state by forces acting upon
- 46. Planar Truss A truss that lies in a single plane often used to support roofs and
- 47. Gusset A plate or bracket for strengthening an angle in
- 48. Simple Truss A truss composed of triangles, which will retain its shape even when removed
- 49. Newton's Third Law If one body exerts a force on a second body, then the second body exerts a force on the first body which is equal in magnitude, opposite in direction, and
- 51. A truss composed of triangles, which will retain its shape even when removed from
- 52. Static
- 53. Magnitude The absolute value of a
- 54. Newton's Second Law The change of motion of the body is proportional to the net force imposed on the body and is in the direction of the net
- 55. Static Equilibrium A condition where there are no net external forces acting upon a particle or rigid body and the body remains at rest or continues at a constant
- $\bf 56.$  Moment The turning effect of a force about a point equal to the magnitude of the force times the perpendicular distance from the point to the line of action from the
- 57. Newton's Third Law If one body exerts a force on a second body, then the second body exerts a force on the first body which is equal in magnitude, opposite in direction, and
- 58. Direction The direction of a vector is defined by the angle between a reference axis and the arrow's line of

## e arrow's tine or

- 1. A structure or body which is over-constrained such that there are more unknown supports than there are equations of static
- $\bf 3.$  Cross-Sectional Area A surface or shape exposed by making a straight cut through something at right angles to the
- 4. Centroid The geometric center of an
- 5. Free Body Diagram A diagram used to isolate a body from its environment, showing all external forces acting upon
- 5. Vector Quantity A quantity that has both a magnitude and

- $\textbf{7. Flange A broad ridge or pair of ridges projecting at a right angle from the edge of a structural shape in order to strengthen or stiffen$
- 8. Concurrent Force Systems A force system where all of the forces are applied at a common point on the body or having their lines of action with a common intersection
- . Tension Force A body subjected to a
- 10. CABLE A strong rope, usually made of metal, designed to have great tensile strength and to be used in
- 14. Moment The turning effect of a force about a point equal to the magnitude of the force times the perpendicular distance from the point to the line of action from the
- 16. Scalar A physical quantity that has magnitude
- 20. Simple
- 22. Moment of Inertia A mathematical property of a cross section that is concerned with a surface area and how that area is distributed about a centroidal
- 24. A support that only prevents a beam from translating in one
- 25. Member Slender straight pieces of a truss connected by
- 26. Method of Joints A method of analysis of trusses which constructs free body diagrams of each joint and determines the forces acting in that joint by considering equilibrium of the joint 29. Roller
- 30. Something made up of interdependent parts in a definite pattern of organization, such as trusses, frames, or
- 31. Pinned Support A support that prevents translation in any
- 32. Tension
- 33. Resultant Force The resultant of a system of force is the vector sum of all
- 34. Sense The sense of a vector is the direction of the vector relative to its path and indicated by the location of the
- ${\bf 36.}$  Resultant Force The resultant of a system of force is the vector sum of all
- 40. Newton's First Law Every body or particle continues at a state of rest or uniform motion in a straight line, unless it is compelled to change that state by forces acting upon
- 50. The sense of a vector is the direction of the vector relative to its path and indicated by the location of the