

Name: _____

Date: _____

VEX and ROBOTC

H S O K X H O U U F U S U B S Y S T E M R U H H
R W P C P X F O T N G W D I S J V W D G O I R C
J S R D R B O R Z D O J G E A A S J N C B U E T
B P A A Z I A X Q B V I U E P S B H F T O B T I
Y J G R F H Z L F K Y Q S E M O T O R Y T D E W
Y H M I C R D U M S U N S I E T H O K P C L M S
C H A W W H U Z T A X L H R C W T U D T H O O T
U P O V C Z F E X T I E T C U E P M A E Q Q I I
J L L V L D S W N K D L T R T O D D T M N R T M
F P U U T R A T S W I G V R A I W D A P A B N I
H C E M S I C C A N K A R Y O S W W U L W V E L
B R J N F E Q B E J E I Q E T C O S W A B U T P
Z C O Q C H R F P R E G G U B E D N R T K W O Z
L K S S E O O V O G J W U W J B D N I E X I P D
E X W W N L D T O E E G N I Z O N A N C P E X U
F D B Q L E O E I A Y N N G G E H F R K N M O I
Z K O O P J S C R R Y P U O X W F V E D N U U D
D A W C B T C L R G U Z B L A P O U D I V E X B
Z E U L O W O N A T L A X A E M B E H A V I O R
R E A E J D G Q M T H L Q N K D H B Q C T Q U Y
R N Z Y P S U T I J I W P A E T I A X N Z G J B
N O R G U G M E D I T G W F Q L F N H V G E A T
S C I T O B O R S U S H I E R U T C U R T S M J
M Z T U P T U O I P R I H D L T B S H T K B S I

digitalsensor
limitswitch
structure
decision
analog
robotc
start
end

potentiometer
pseudocode
subsystem
robotics
cortex
input
data
vex

bumperswitch
ultrasonic
behavior
template
output
motor
gear

linefollower
flowchart
debugger
encoder
pragma
servo
task